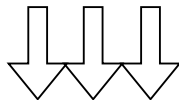
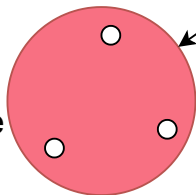


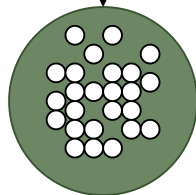
Incoming Data



Noise/Outlier
(Data points with no close
neighbours)



Existing Cluster
(Merges based on similarity)



New Cluster
(Distinct dense patterns
lead to new cluster)

